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for analyzing a digital control system. As shown in Figure L.1, the z-transform enables the engineer to combine a continuous process and digital controller into one transfer function model. As with continuous systems, we can use the

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transfer function model to determine important properties of the system, such as its stability,

Analysis of Digital Control Systems

This class will provide a comprehensive treatment of the analysis and design of discrete-time control systems. The course will build upon the student's

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First, the magnetic suspension system is stabilized using a digital proportional-derivative controller. Subsequently, the digital model is identified using recursive

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algorithms. Finally, a digital mixed linear quadratic regulator (LQR)/ H^∞ control is adopted to stabilize the magnetic suspension system robustly.

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The chapter on control design in the

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frequency domain (Chapter 8) is, in my opinion, far the worse because it is, in fact, a chapter on CONTINUOUS control design (use of bilinear transformation from z to w and design in w).

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Find the z-transforms of the number sequences generated by sampling the following time functions every Tseconds, beginning at t= 0.

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